



USEPE : U-SPACE SEPARATION IN EUROPE

17 May 2022
UAM for all workshop



This project has received funding from the SESAR Joint Undertaking under grant agreement No 890738 under European Union's Horizon 2020 research and innovation programme






24 months

January 2021 — December 2022

7 partners

↓

4 countries

 **Isdefe**
your best ally

Project coordinator

H2020-SESAR-2019-2
H2020 Call



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Why does USEPE exist?

SESAR 3 Joint Undertaking

- ⇒ institutionalized EU partnership
- ⇒ R&I for Digital European Sky.

Digital European Sky

- ⇒ latest digital technologies in aviation infrastructure
- ⇒ Enable growth & diversity handling + minimize environmental impact



What does USEPE do?

Develop a method to ensure the safe separation of drones over urban areas.

⇒ Concept of operations (documentation)

⇒ Enabling technologies (Machine-learning & AI)



Why is USEPE needed?

Increasing number of use cases for drones in urban areas.

- ⇒ Monitoring: Inspection of constructions, electrical lines, fishing, fires...
- ⇒ Saving: Medical deliveries, emergency situations
- ⇒ Accessing: Delivery or travel in remote areas



What can we do ?

- Monitoring → image processing from image of the camera → Inspection of electrical line, fishing, fire ect...
- Health Care → Medical deliveries (for ex. During Covid Pandemia) Zipline delivers more Than 70 000medical devices using drones
- Urban air mobility (transport people, goods, ect...)
- Military purpose

Why ?? NOW ? FUTURE? Techonology

Drones as the future for urban air mobility?

Drones ?? An unmanned aerial vehicle (UAV) or Drones



(a)



(b)



(c)





1. Few elements of context

What is the U-Space?

- A set of new **services** (Geo-awareness, flight authorization, traffic & weather information...)
- Supporting **safe, efficient and secure access** to airspace for large numbers of drones
- Relying on a high level of **digitalisation and automation** of functions and specific procedures



Increasing drones use cases





USEPE main topics to tackle

- Conflict detection - Conflict resolution
- Airspace capacity
- Traffic demand
- Meteorology (micro weather)
- Airspace optimisation
- Ground structure (buildings, streets, open spaces)
- Availability of communications (obstacles)
- Geofenced/forbidden areas (fixed or sudden ones)



1. USEPE project Uospace separation for Europe

A concept of drone's operations in urban environment D2C2 concept

2. Socio-technical considerations for urban air Mobility

3. Conclusion



1. USEPE project: U-space separation for Europe



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USEPE partners



indra



Isdefe



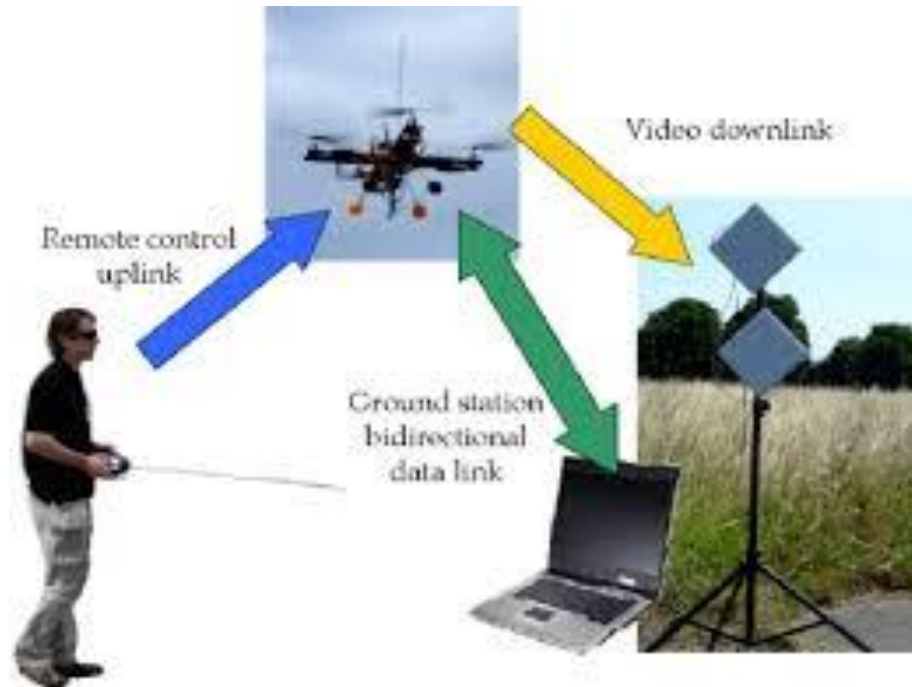
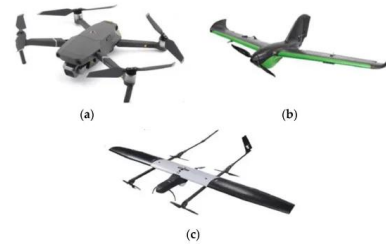
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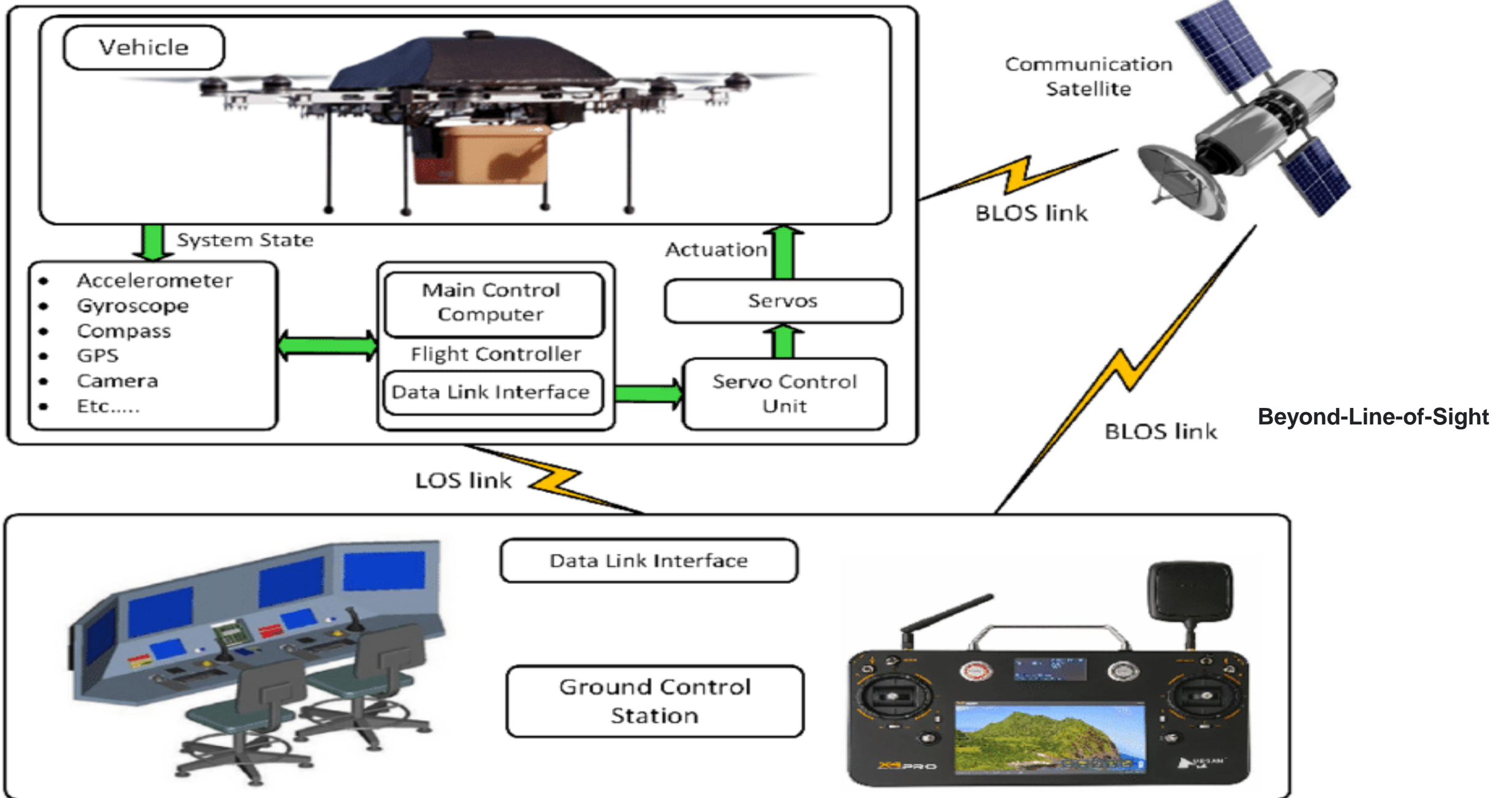
POLIS
CITIES AND REGIONS FOR TRANSPORT INNOVATION

USN University of
South-Eastern Norway

Drones as the future for urban air mobility?

Remote or Autonomous

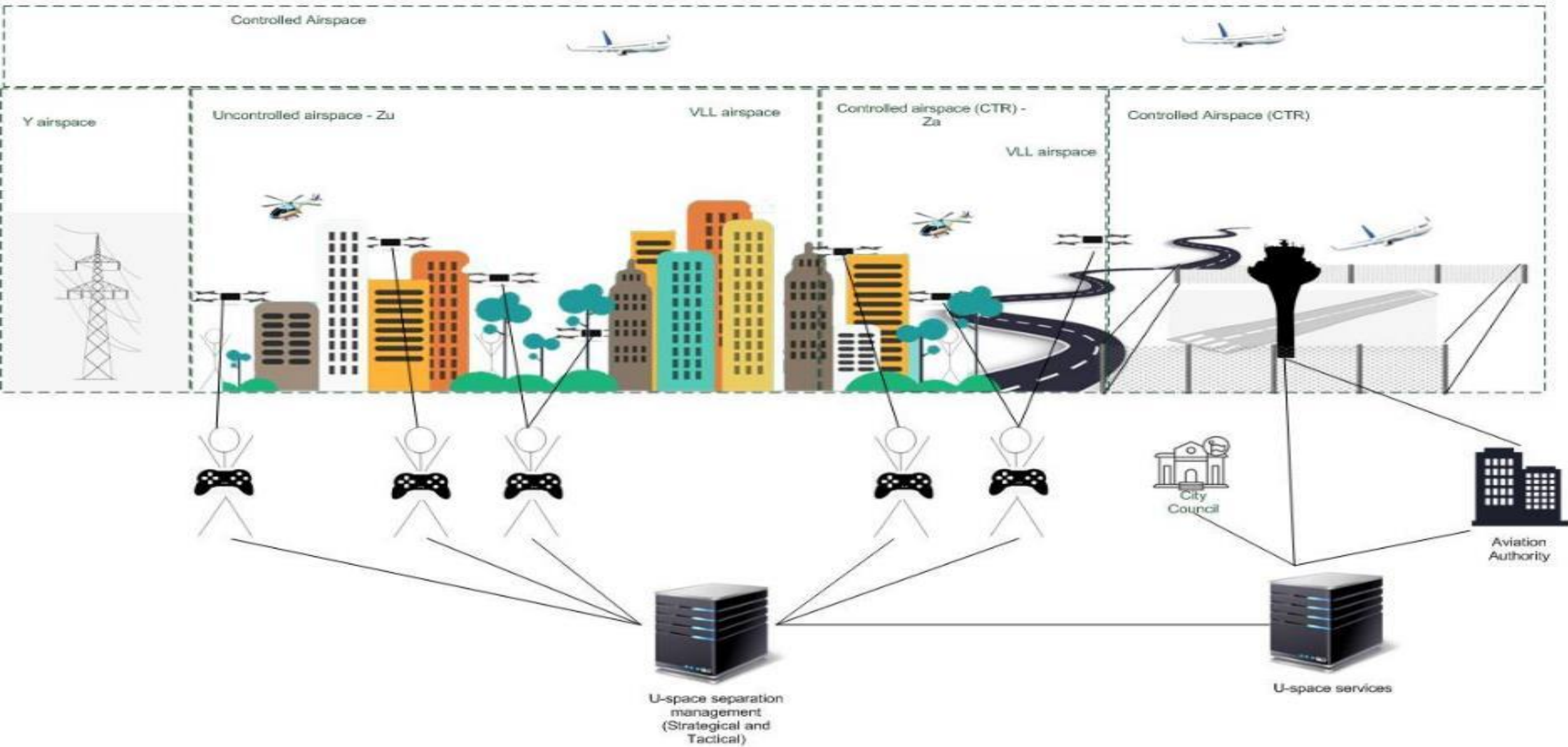


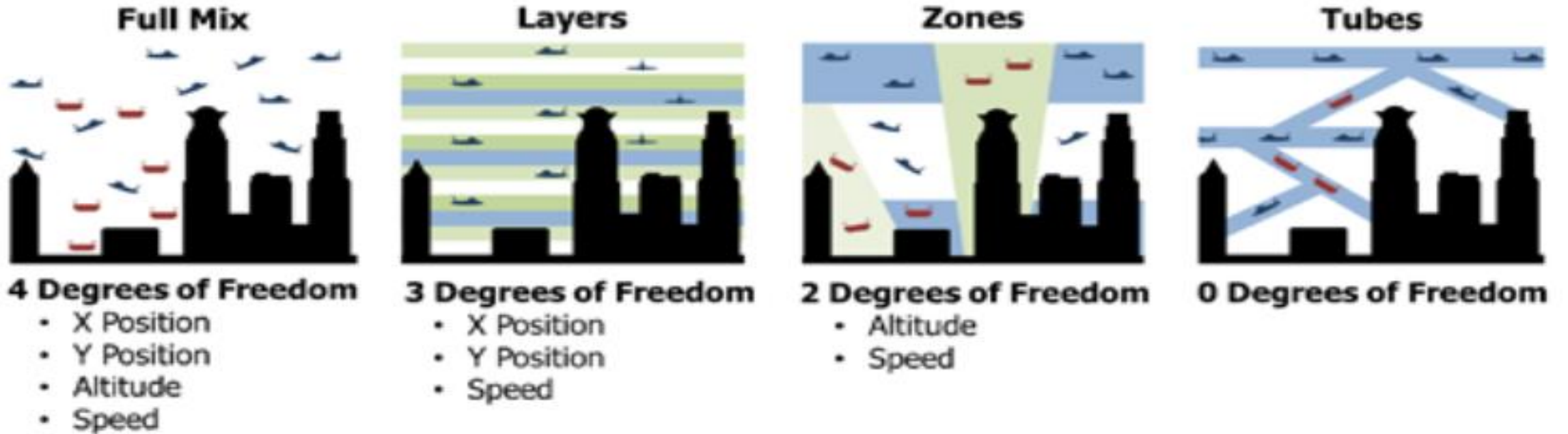




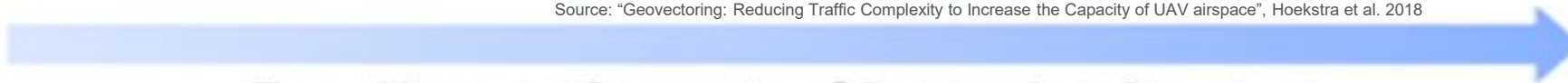
DRONE-PILOT

Sharing the airspace ?

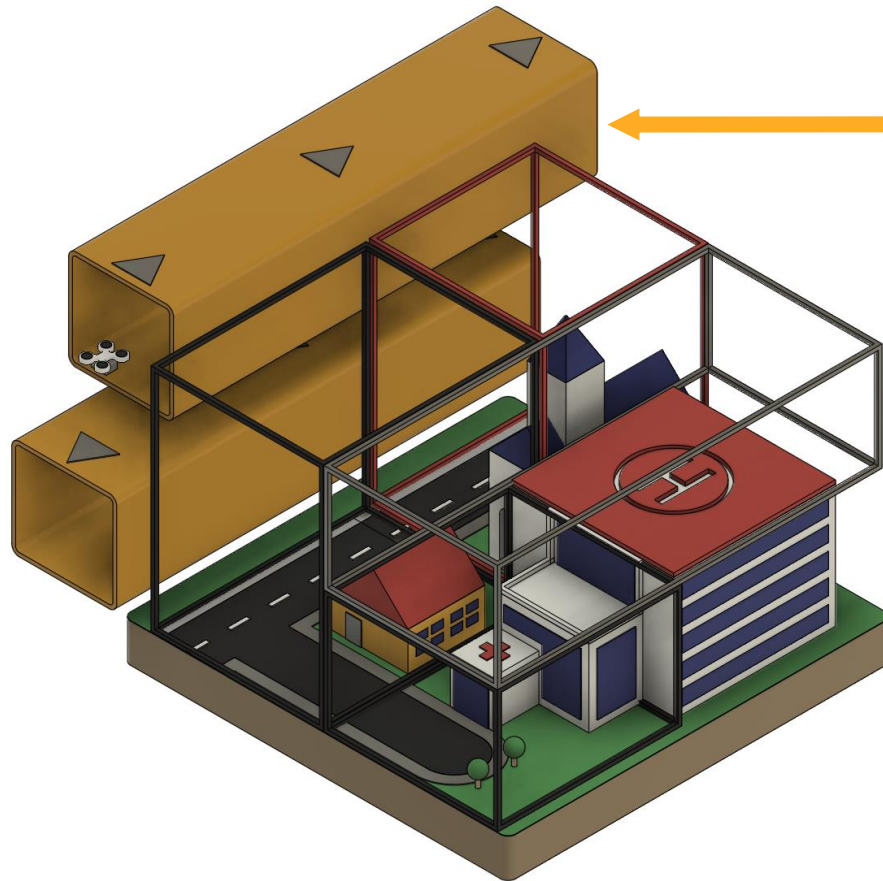




Source: "Geovectoring: Reducing Traffic Complexity to Increase the Capacity of UAV airspace", Hoekstra et al. 2018



Four Airspace Concepts of Increasing Structure



High Speed Corridors

- **Static corridors** with strict limitations (**velocity/direction**)
- **Reduction of relative velocity** between UAS
- Considers **ground risks** and **environment** (e.g. noise)

Density-Based Airspaces

- **Dynamic segments** sized on various characteristics
- **Deconfliction** capability drives **capacity**
- Limitations for entering **may** apply based on demand

Geovectoring

- Set of requirements for **speed, heading, rate of climb**
- Manage **traffic complexity**, instead of **density**
- Applicable only in **corridors** and **specific segments**

2. socio-Technical consideration of drone's operation in Urban enviroment



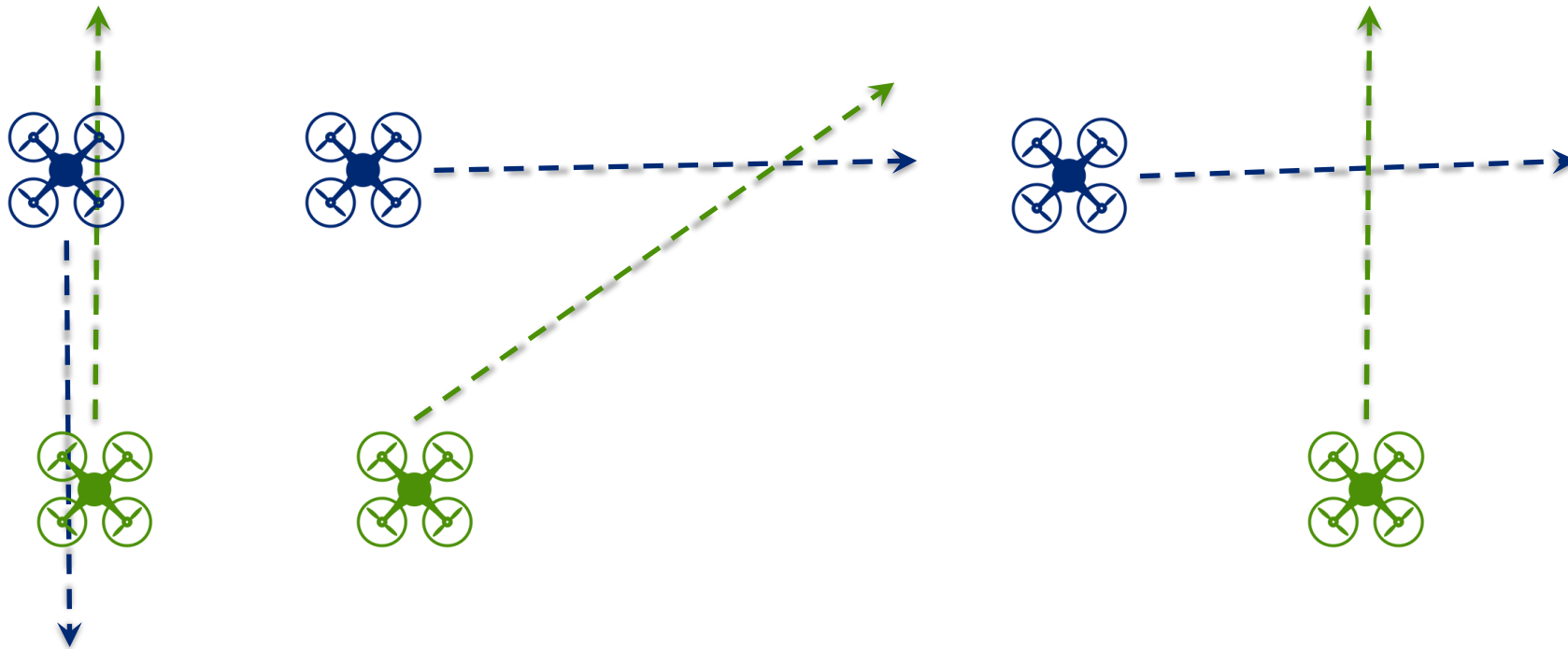
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Challenges to overcome:

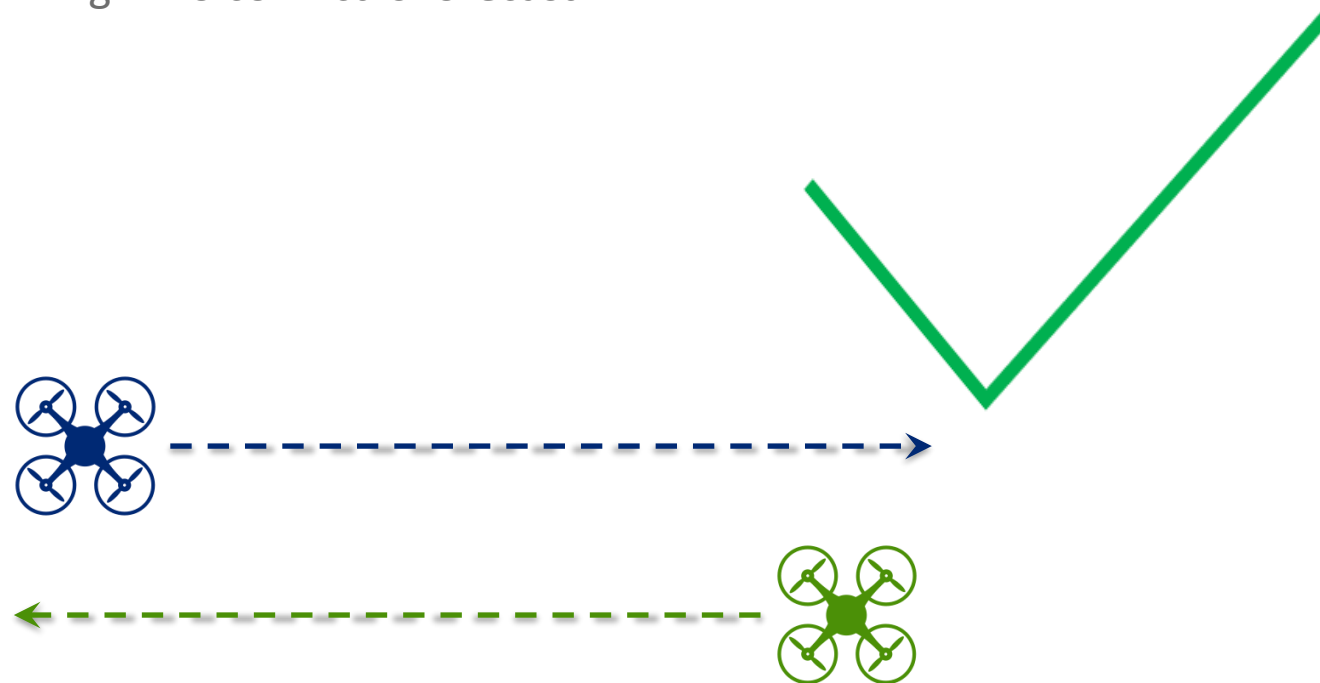
- A safe separation
- Conflict detection
- Autonomous flights
- Communication
- Conops delineation
- Urban airspace specification



Possible flight route conflicting → Intersecting routes are easily identifiable.

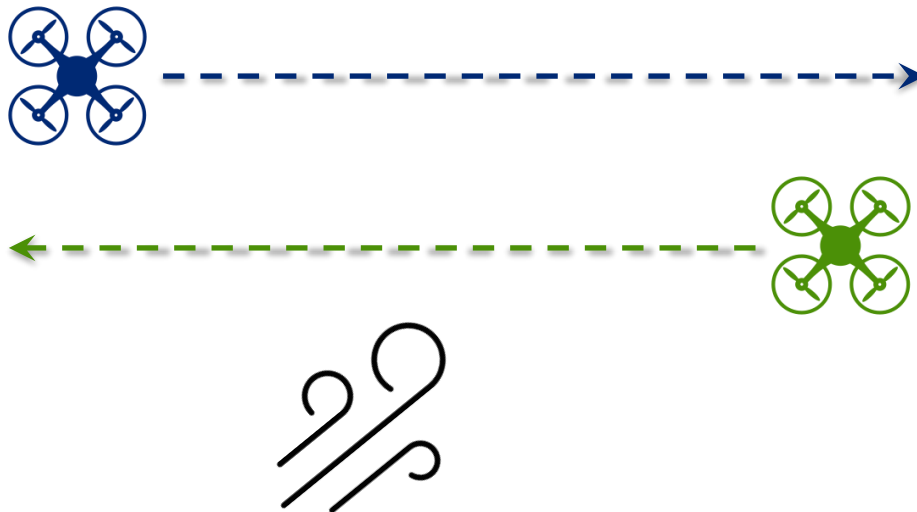


Drone's Flight planning .. No conflict is forecast



Real Time flight ?

Several unexpected events could occur! Such for instance WIND?



Failure of drones

Loss of communication

Weather conditions

Human errors

Mission priorities

Realtime closure of airspace →

Rerouting

Real time control ??

Autonomous?

We explore the use of In the Machine Learning approach and we identify the drones which are most likely to intervene with other drones.

For that purpose, the ML algorithm considers measures such as route, timing, speed, wind, etc. from past experiences (training data) to predict the probability of conflict in future situations.

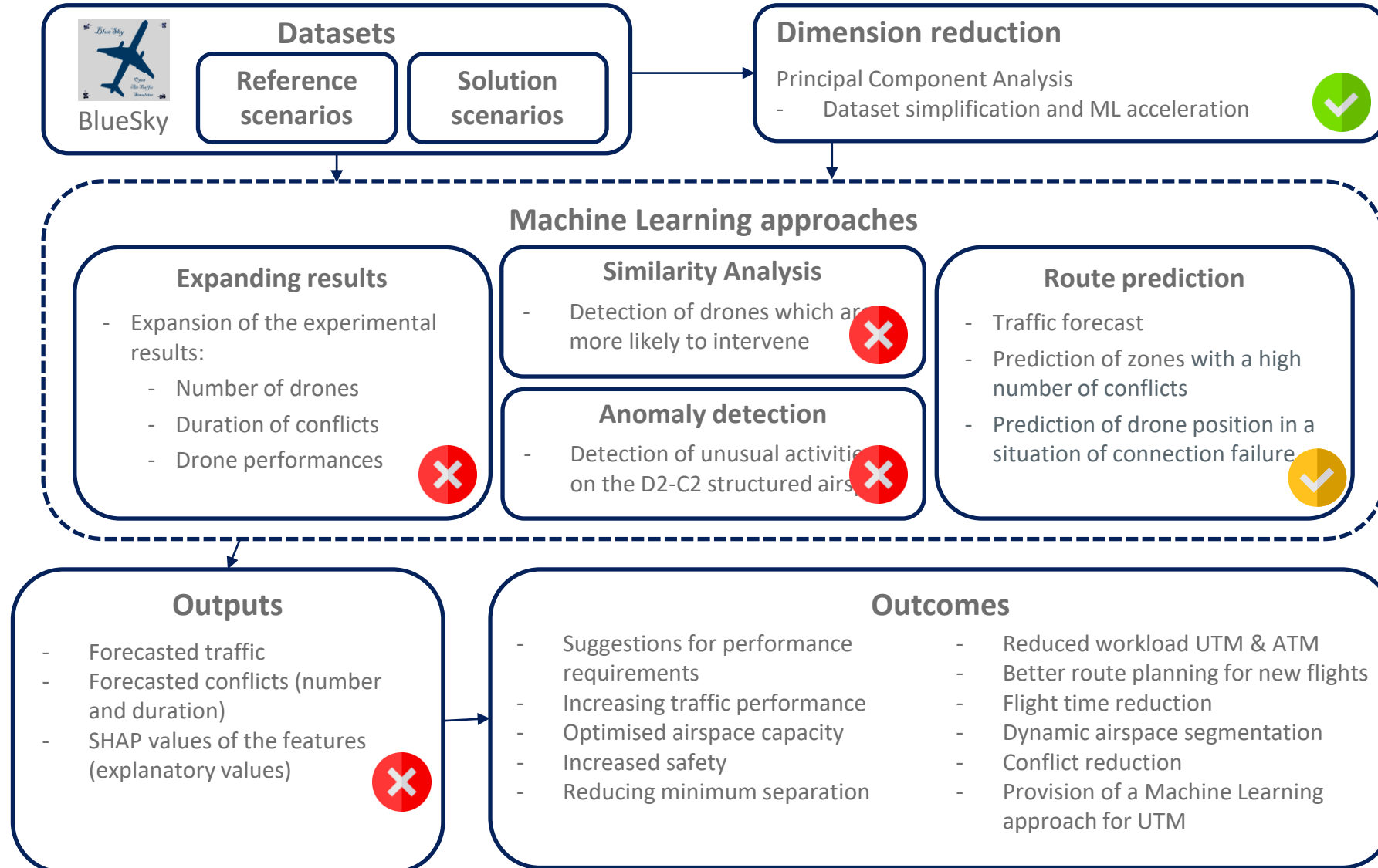
For example,

Less distances, less safety



More distance, more safety





Drones → Hardware (sensors, Actuators, Camera, ect..) and Software

→ USE of ML at the Drones operation Level

- Huge number of drones, Flights plans → Automatic flight scheduling and approval (detect if any possible conflicts)
- DAA (Detect And Avoid) system on board? ML to analyze in Real Time data from different sensors that are attached to drones
- Automatic Rerouting in case of Drones failure
- Decision making during flight drones if unpredictable event occurs
- Automatic distance separation to insure a separation minima between drones and Manned traffic
- Ect...



several questions need to be tackled

- **Can citizen trust AI-based Systems such as autonomous drones??**
- **Is It possible to integrate the ethical dimension of AI (transparency, non-discrimination, fairness, non-discrimination etc.) in safety processes?**
- **How AI could be taken into account in standards or so that the level of safety of drones operation in Urban environment is Improved?**
- **Accountability, Liability in case of Accident?**
- **Security, Privacy,**

4. Conclusion



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In summary

ML for better Safety of drones operation in Urban environment

ML for airspace use optimisation (noise, level of acceptance of citizens, type of mission, geofenced areas, ect..)

Dynamic airspace reconfiguration

➔ Ethics dimensions of not only using drones but as well on AI foundation



Drones applications and emerging technology is opening up a new way to look into Urban air Mobility that could reduce for i.e the print carbone, or increase job market opportunities but in same time they are socio-technical challenges of drone operations in densiely populated areas.



U-space SEParation in Europe

Attend the live simulation of our new drones' separation method: D2-C2 !

OPEN SIMULATION DAY

[Register HERE](#)

Dynamic Density Corridor Concept is a fusion of separation methods for safe and efficient drone traffic in urban environment.



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Online, June 16, 10:00 AM

How can the concept be validated by BlueSky simulations?

How can machine learning contribute to a safer U-space?

How do we assess the wind impact on separation using simulations?

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Thanks You
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Can we stop the
advancement ?

